

8.7.9

$$\dot{r} = r(1-r) \quad \dot{\theta} = 1$$

$$e) \quad \theta = t + \theta_0$$

$$\theta(0) = 0 + \theta_0 = \pi/2$$

$$\theta = t + \pi/2$$

Partial
Fractions

$$\frac{dr}{r(1-r)} = dt$$

$$\left(\frac{1}{r} + \frac{1}{1-r}\right) dr = dt$$

$$\ln r - \ln(1-r) = t + c$$

$$\frac{r}{1-r} = e^{t+c}$$

$\Rightarrow$

$$r(t) = \frac{r_0 e^t}{(1-r_0) + r_0 e^t}$$

$$b) \quad r(2\pi) = \frac{r_0 e^{2\pi}}{(1-r_0) + r_0 e^{2\pi}}$$

$$\Rightarrow r_{n+1} = \frac{r_n e^{2\pi}}{(1-r_n) + r_n e^{2\pi}}$$

(Note, that $\theta_0 = \pi/2$ doesn't make a difference)

$$c) \quad r_f = \frac{r_f e^{2\pi}}{(1-r_f) + r_f e^{2\pi}}$$

$$r_f(1-r_f)(1-e^{2\pi}) = 0$$

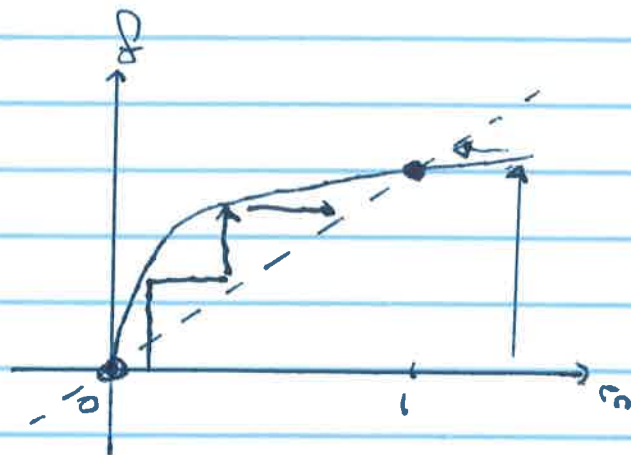
$$r_f = 0, 1$$

$$d) \quad f = \frac{r e^{2\pi}}{(1-r) + r e^{2\pi}}$$

$$f' = \frac{e^{2\pi}}{[1 + (e^{2\pi}-1)r]^2}$$

$$f'(0) = e^{2\pi} > 1 \Rightarrow U$$

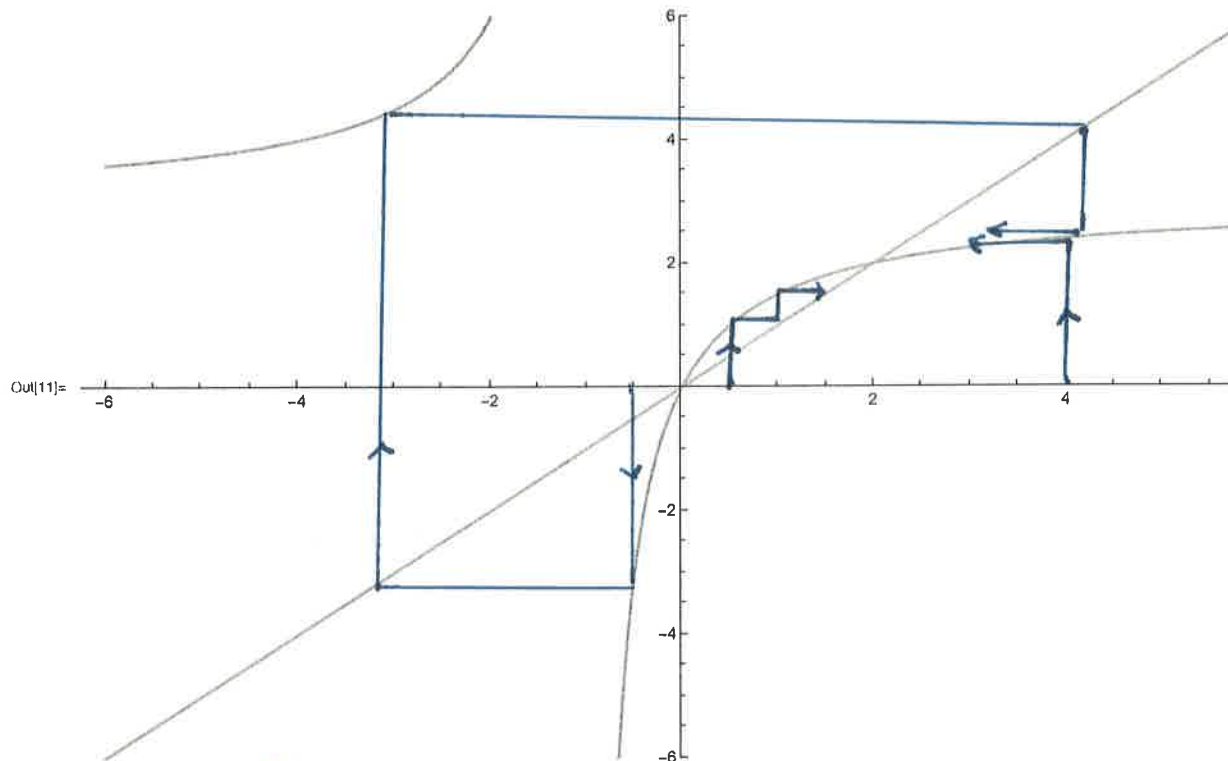
$$f'(1) = \frac{1}{e^{2\pi}} < 1 \Rightarrow S$$



Note, in general we should consider r neg as well. However, in this case r corresponds to the radius of a L.C., which is positive.

10.1.9

In[11]:= Plot[{3 * x / (1 + x), x}, {x, -6, 6}, PlotRange -> {-6, 6}]



$$x_{n+1} = \frac{3x_n}{1+x_n}$$

$$x_f = \frac{3x_f}{1+x_f}$$

$$x_f(x_f - 2) = 0$$

$$x_f = 0, 2$$

$$f(x) = \frac{3x}{1+x}$$

$$f'(x) = \frac{3}{(1+x)^2}$$

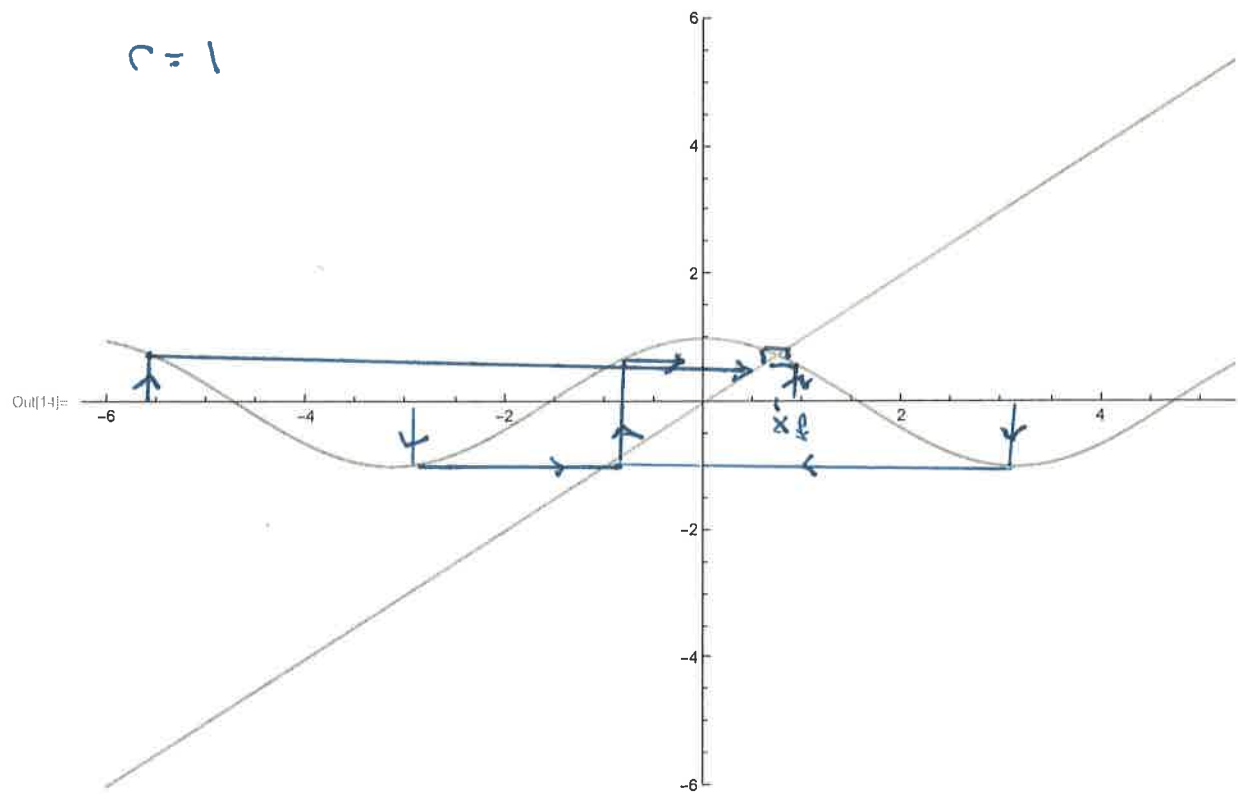
$$f'(0) = 3 > 1 \Rightarrow U$$

$$f'(2) = \frac{1}{3} < 1 \Rightarrow A. \text{Stable}$$

2 | 10.1.12

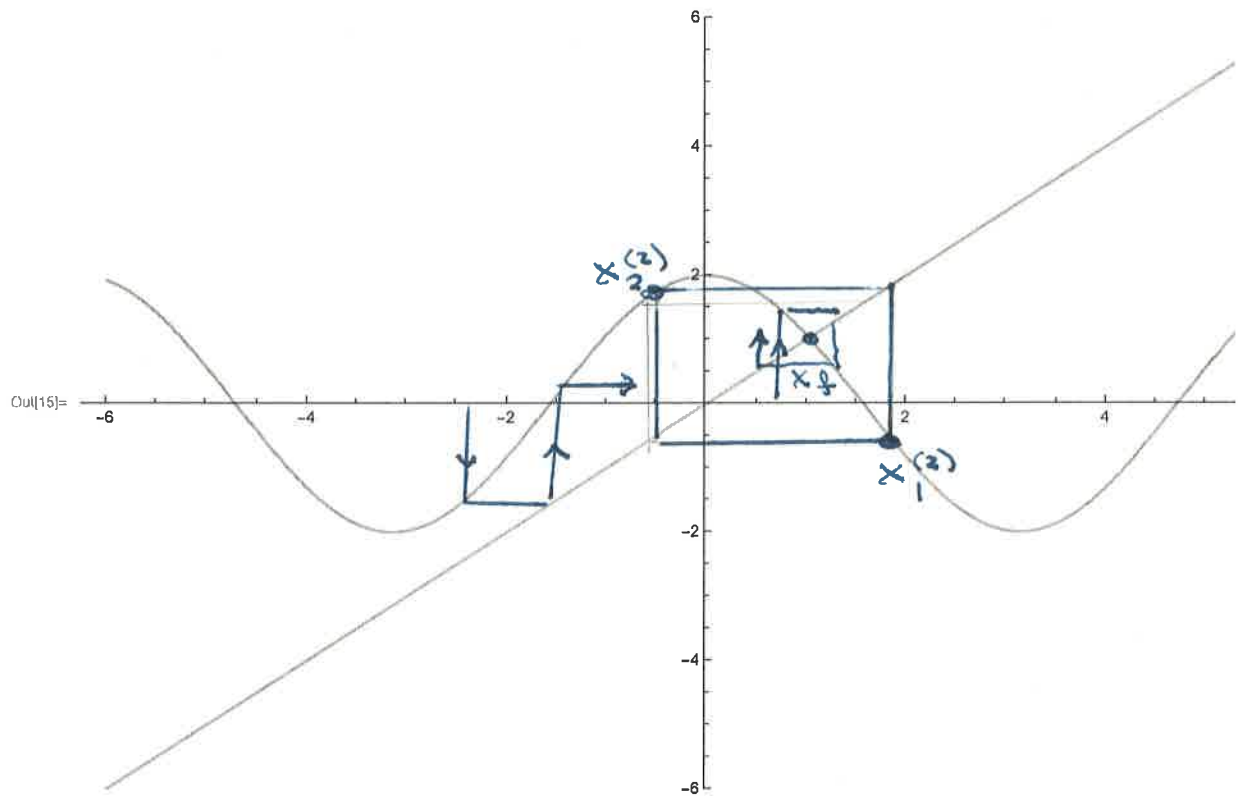
In[14]:= Plot[{Cos[x], x}, {x, -6, 6}, PlotRange -> {-6, 6}]

$c = 1$



All ICs go to x_f

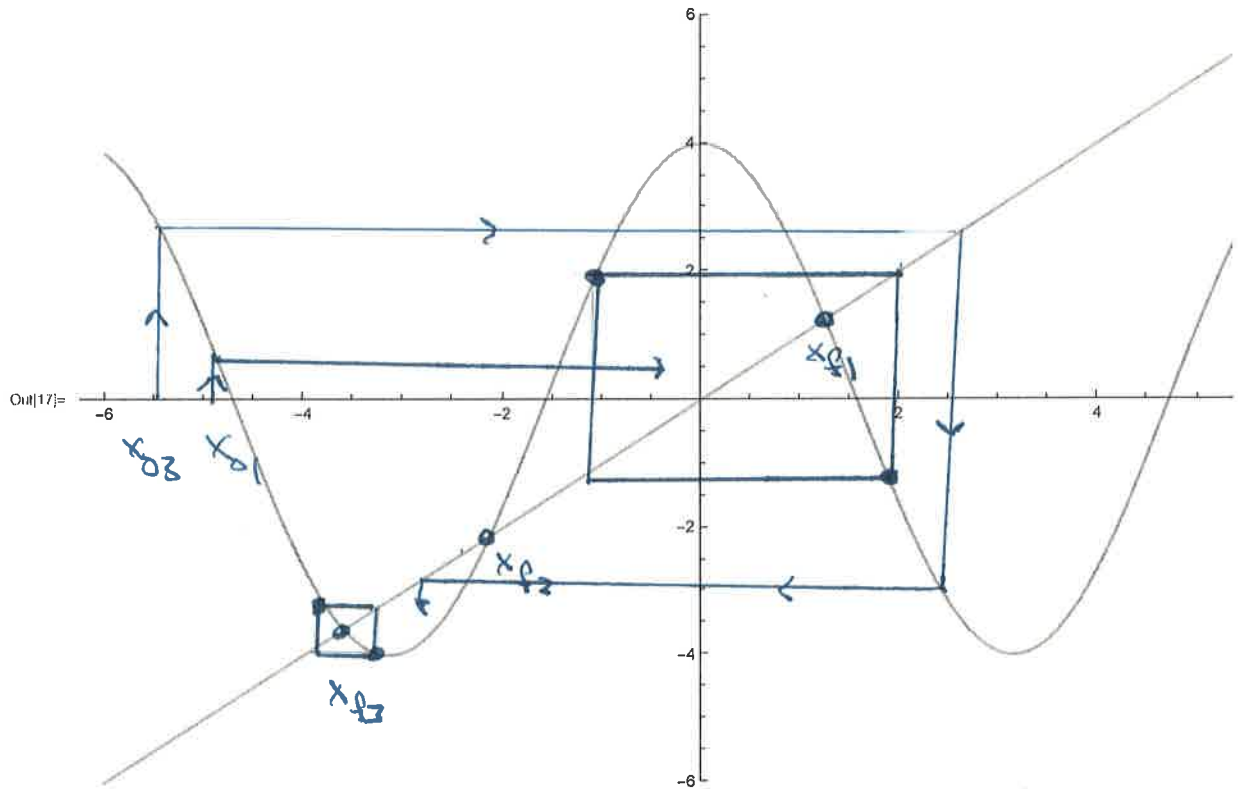
In[15]:= Plot[{2 * Cos[x], x}, {x, -6, 6}, PlotRange -> {-6, 6}]



Separately, I plot $f^{(2)}(x) = 2 \cos[2 \cos(x)]$ and located F.P. of $f^{(2)}$. These are period-2 pts of $f(x)$.

x_f appears to be unstable while the period-2 cycle $\{x_1^{(2)}, x_2^{(2)}\}$ is stable.

In[17] = Plot[{4 * Cos[x], x}, {x, -6, 6}, PlotRange -> {-6, 6}]



Again, I found the period-2 cycle by examining $f(z)$. The larger constant (4 instead of 2) has produced two new F.P. x_{f2} & x_{f3} .

Both x_{f1} & x_{f3} have period-2 cycles around them. The slope at x_{f2} is > 1 and so unstable. However, the slope is pos. and so there won't be a flip saddle or higher period cycles.

Notice, x_{o1} & x_{o3} start very close. However x_{o1} eventually goes to the P2 cycle around x_{f1} , whereas x_{o3} goes to the P2 cycle around x_{f3} .

10.1.12

$$x_{n+1} = f(x_n) = x_n + \frac{g(x_n)}{f'(x_n)}$$

If $g(x) = x^2 + 4$, $g'(x) = 2x$

$$x_{n+1} = x_n - \frac{(x_n^2 + 4)}{2x_n} = \frac{x_n^2 + 4}{2x_n}$$

$$x_f = \frac{x_f^2 + 4}{2x_f} \Rightarrow x_f = \pm 2$$

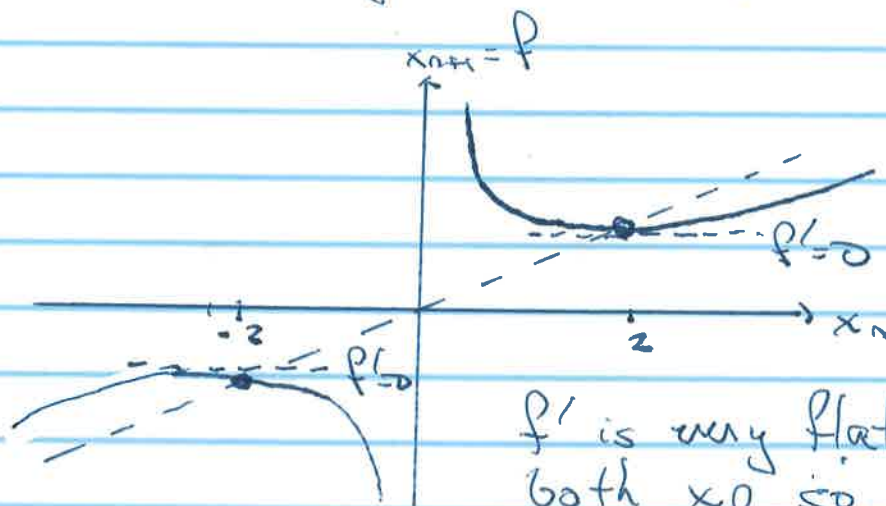
$$f'(x) = \frac{x^2 - 4}{2x^2} \quad f'(\pm 2) = 0 \rightarrow \text{Superstable.}$$

Suppose $x_0 = 1$

$$x_1 = \frac{1+4}{2} = \frac{5}{2} = 2.5$$

$$x_2 = \frac{41}{20} = 2.05$$

After just 2 iterates, already very close to $x_f = 2$



f' is very flat near both x_f so the cobweb will show ICs rapidly "moving" horizontally to x_f

10.3.4

$$x_{n+1} = x_n^2 + c$$

F.P.: $x_f = x_f^2 + c$

$$x_f^2 - x_f + c = 0 \quad x_f = \frac{1}{2}(1 \pm \sqrt{1-4c})$$

If $c < 1/4$, there exist 2 solutions x_+ & x_-

If $c > 1/4$, there are no real solutions.

Suggest a Saddle-Node type bif. at $c = 1/4$

L.S. $f'(x) = 2x$

x_+ : $-1 \overset{?}{<} 2\left(\frac{1}{2} + \sqrt{1-4c}\right) \overset{?}{<} 1$
 $-2 < \sqrt{1-4c} < 0$

Assuming $\sqrt{\quad}$ is always pos so neither is ever satisfied. In other words $\sqrt{1-4c} > 0$ always, which means $f'(x_+)$ is > 1 always. $\therefore$ always Unstable.

x_- : $-1 \overset{?}{<} 2\left(\frac{1}{2} - \sqrt{1-4c}\right) \overset{?}{<} 1$
 $-2 < -\sqrt{1-4c} < 0$
 $2 > \sqrt{1-4c} > 0$
 $4 > 1-4c > 0$
 $3 > -4c > -1$
 $-3/4 < c < 1/4$

x_- is stable if $-3/4 < c < 1/4$.

If $c > 1/4$ x_- doesn't exist.

If $c = -3/4$ there is a FLIP BIF

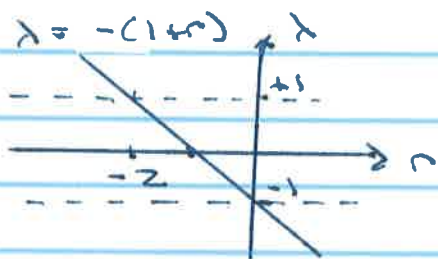
Expect a period 2 cycle for $c < -3/4$

10.3.11

$$x_{n+1} = f(x_n) = -(1+r)x_n - x_n^2 - 2x_n^3$$

a) $x_f = 0$ is an F.P.

b) $y_{n+1} = f'(0)y_n = (- (1+r) - 2x - 6x^2) \Big|_{x=0} y_n$



$$\begin{aligned} \lambda &= -(1+r) \\ &= -(1+r)y_n \\ &= \lambda y_n \end{aligned}$$

$x_f = 0$ is A. Stable for $-2 < r < 0$
At $r = -2$ there is a Bif. (steady)
At $r = 0$ there is a FLIP BIF

c)
$$\begin{aligned} f'(x) &= -(1+r) [- (1+r)x - x^2 - 2x^3] \\ &\quad - [- (1+r)x - x^2 - 2x^3]^2 \\ &\quad - 2 [- (1+r)x - x^2 - 2x^3]^3 \end{aligned}$$

For $x \ll 1$ and $r \ll 1$ (x near $x_f = 0$ and r near $r_c = 0$)

keep only the biggest terms.

$$f'(x) \approx (1+2r)x - x^2 + O(r^2x, rx^2, x^3)$$

so 2ND iterate map is approx

$$u_{n+1} = (1+2r)u_n - u_n^2$$

$$u_f = (1+2r)u_f - u_f^2$$

$$\begin{aligned} 0 &= u_f(2r - u_f) & u_f = 0 &\equiv x_f \\ & & u_f &= 2r \end{aligned}$$

When $x_f = 0$ has a flip bif we expect 2 new fixed points of $f'(x)$. We only got one, $u_f = 2r$. To "see" the other we have to zoom out and keep some cubic terms.

Note $\lim_{r \rightarrow 0} (u_f = 2r) = (0 = x_f)$

∴ As $r \rightarrow 0$ the P2 cycle collides w/ x_f

a) For $r < 0$ x_f is A-stable so
 $\lim_{n \rightarrow \infty} x_n = x_f$

For $r > 0$ x_f is Unstable. The
orbit will converge to the P2 cycle
w/ $u_f = 2r$ (and the other P2 point).