

# Math 6391 nos-delayneuron.gif

$\mu = 0$

$\rightarrow \cancel{1, 2 \text{ or } 3 \text{ equal.}}$

$$b) \frac{1}{3}r_0^3 + (\frac{1}{b} - 1)r_0 + \frac{2}{b} = 0$$

$$c) \lambda^2 + \lambda(r_0^2 - (1-\rho b)) + \rho(1-b(1-r_0^2)) = 0$$

$$2\lambda = - (r_0^2 - (1-\rho b)) \pm [ (r_0^2 - (1-\rho b))^2 - 4\rho(1-b(1-r_0^2)) ]^{1/2}$$

$$\text{Stable-focus: } r_0^2 - (1-\rho b) > 0 \Rightarrow r_0^2 > 1 - \rho b$$

$$(r_0^2 - (1-\rho b))^2 - 4\rho(1-b(1-r_0^2)) < 0$$

$$\Rightarrow r_0^2 < 1 + \rho b + 2\sqrt{\rho}$$

$\mu \neq 0$

a) Same as above. Use maple to compute

$$b) \lambda^2 + \lambda(\rho b - 1 + r_0^2) + \rho(1 + b(r_0^2 - 1)) + (-\lambda\mu - \rho bu)e^{-\lambda t} = 0$$

$$c) \text{let } \lambda = i\omega$$

$$\omega^2 - \rho(1 + b(r_0^2 - 1)) = \mu(\rho b \cos \omega t + \omega \sin \omega t)$$

$$\omega(\rho b - 1 + r_0^2) = \mu(\omega \cos \omega t - \rho b \sin \omega t)$$

$$\text{let } b_1 = \omega^2 - \rho(1 + b(r_0^2 - 1))$$

$$b_2 = \rho b - 1 + r_0^2$$

$$\text{Then } \cos \omega t = -\frac{\omega^2}{\mu \rho b} \frac{(b_2 \rho b - b_1)}{\omega^2 + \rho^2 b^2} + \frac{b_1(\omega^2 + \rho^2 b^2)}{\omega^2 + \rho^2 b^2}$$

$$\sin \omega t = -\frac{\omega(b_2 \rho b - b_1)}{\mu \rho b(\omega^2 + \rho^2 b^2)}$$

- $\tan \omega t = f_1(\omega)$  eliminates  $\mu$

Multiple solutions  $\Rightarrow$  many values of  $\omega$ .

- $\cos^2 \omega t + \sin^2 \omega t = 1 \Rightarrow \mu^2 = f_2(\omega)$

Equation for  $\mu$  in terms of  $\omega$ .

