

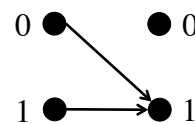
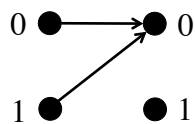
## Deutsch's Problem

- Black Box Characterized by Transfer Function that Maps Single input Bit  $x$  to Output Bit  $f(x)$
- Transformation Performed by Black Box Could be Any of the Four Possible Boolean Functions of One Variable (pick a pair of  $f(0)$  and  $f(1)$ ):  
 $f(0) = 0 \quad f(0) = 1 \quad f(1) = 0 \quad f(1) = 1$
- Problem Posed by Professor David Deutsch is to Distinguish if:

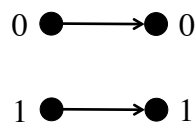
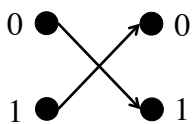
$$f(0) = f(1) \quad \text{OR} \quad f(0) \neq f(1)$$

## Deutsch's Problem

- Four cases for  $f(x)$ :

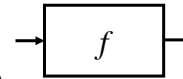


Unbalanced:  $f(0) = f(1)$

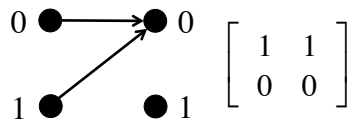


Balanced:  $f(0) \neq f(1)$

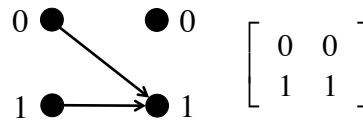
## Deutsch's Problem



- What are the transfer matrices for  $f(x)$ ?

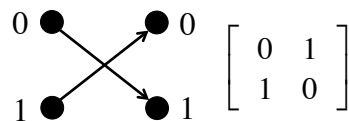


$$\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

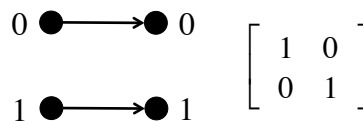


$$\begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}$$

Unbalanced:  $f(0) = f(1)$



$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$



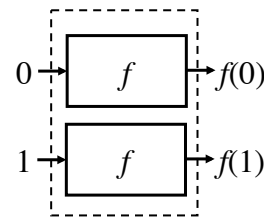
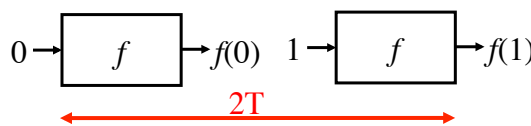
$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Balanced:  $f(0) \neq f(1)$

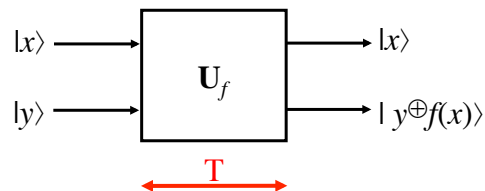
## Deutsch's Problem

- Assume Comparison of Function Evaluation takes no Time:

- Classical Approaches:

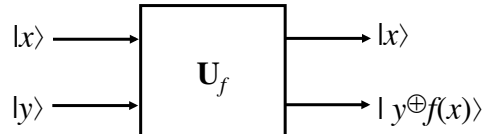


- Quantum Approach:



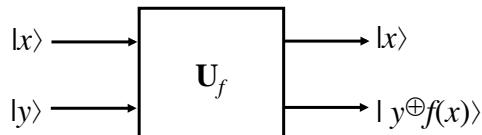
## Deutsch's Problem

- $f(x)$  is “embedded” inside  $U_f$  “gate” or operator but the actual  $f(x)$  embedded is unknown:
- Denoted by:



- There are four different  $U_f$  gates, but it is unknown which is present

## Synthesis of $U_f$ Operators



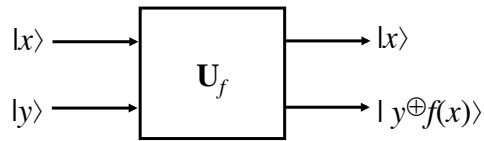
- Use the following notation:

$$f_0 = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \quad f_1 = \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \quad f_{01} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad f_I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

- Truth tables for  $U_f$ :

$x$	$y$	$f_0$	$y \oplus f_0$	$f_1$	$y \oplus f_1$	$f_{01}$	$y \oplus f_{01}$	$f_I$	$y \oplus f_I$
0	0	0	0	1	1	1	1	0	0
0	1	0	1	1	0	1	0	0	1
1	0	0	0	1	1	0	0	1	1
1	1	0	1	1	0	0	1	1	0

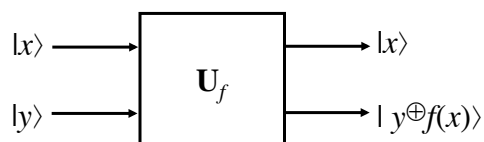
## Synthesis of $U_{f0}$



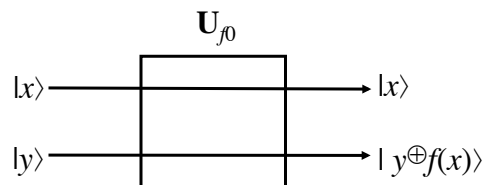
$x$	$y$	$f_0$	$y \oplus f_0$	$f_1$	$y \oplus f_1$	$f_{01}$	$y \oplus f_{01}$	$f_1$	$y \oplus f_1$
0	0	0	0	1	1	1	1	0	0
0	1	0	1	1	0	1	0	0	1
1	0	0	0	1	1	0	0	1	1
1	1	0	1	1	0	0	1	1	0

$$U_{f0} = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

## Synthesis of $U_{f0}$

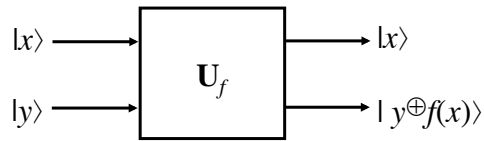


$$U_{f0} = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$



$$U_{f0} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

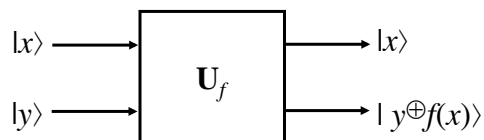
## Synthesis of $U_{f1}$



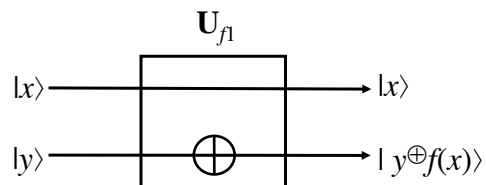
$x$	$y$	$f_0$	$y \oplus f_0$	$f_1$	$y \oplus f_1$	$f_{01}$	$y \oplus f_{01}$	$f_1$	$y \oplus f_1$
0	0	0	0	1	1	1	1	0	0
0	1	0	1	1	0	1	0	0	1
1	0	0	0	1	1	0	0	1	1
1	1	0	1	1	0	0	1	1	0

$$U_{f1} = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

## Synthesis of $U_{f1}$

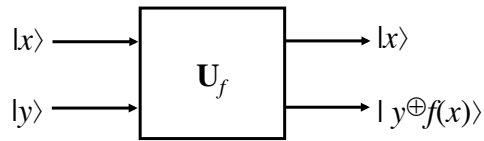


$$U_{f1} = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$



$$U_{f1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \otimes \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

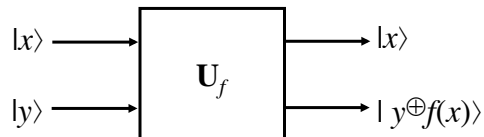
## Synthesis of $U_f$



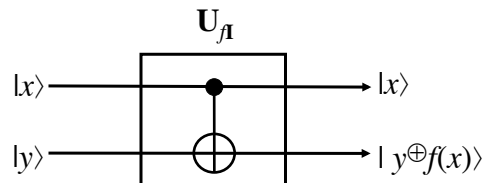
$x$	$y$	$f_0$	$y \oplus f_0$	$f_1$	$y \oplus f_1$	$f_{01}$	$y \oplus f_{01}$	$f_1$	$y \oplus f_1$
0	0	0	0	1	1	1	1	0	0
0	1	0	1	1	0	1	0	0	1
1	0	0	0	1	1	0	0	1	1
1	1	0	1	1	0	0	1	1	0

$$U_f = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

## Synthesis of $U_f$

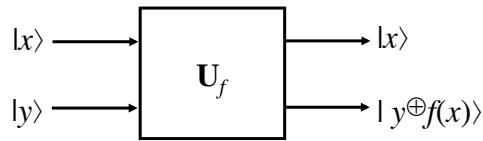


$$U_f = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$



*Controlled-NOT Gate*

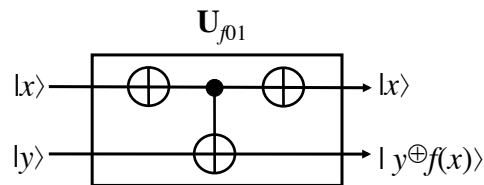
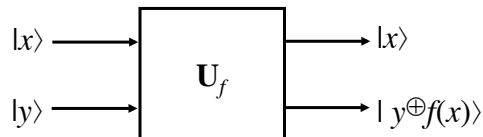
## Synthesis of $U_{f01}$



$x$	$y$	$f_0$	$y \oplus f_0$	$f_1$	$y \oplus f_1$	$f_{01}$	$y \oplus f_{01}$	$f_1$	$y \oplus f_1$
0	0	0	0	1	1	1	1	0	0
0	1	0	1	1	0	1	0	0	1
1	0	0	0	1	1	0	0	1	1
1	1	0	1	1	0	0	1	1	0

$$U_{f01} = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

## Synthesis of $U_{f01}$



$$U_{f01} = \begin{matrix} & 00 & 01 & 10 & 11 \\ \begin{matrix} 00 \\ 01 \\ 10 \\ 11 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

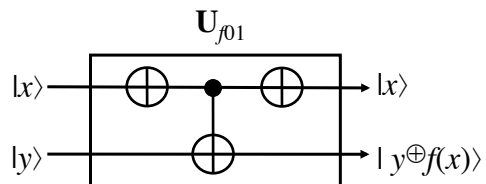
$$U_{f01} = \left( \left( \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \left( \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \right)$$

## Synthesis of $U_{f01}$ (cont)

$$\begin{aligned}
 \mathbf{U}_{f01} &= \left( \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \left( \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \right) \left( \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \\
 \mathbf{U}_{f01} &= \left( \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \right) \left( \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \right) \left( \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \right) \\
 \mathbf{U}_{f01} &= \left( \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \right) \left( \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \right)
 \end{aligned}$$

## Synthesis of $U_{f01}$ (cont)

$$\begin{aligned}
 \mathbf{U}_{f01} &= \left( \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \right) \left( \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \right) \\
 \mathbf{U}_{f01} &= \left( \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \right)
 \end{aligned}$$





## Quantum Algorithm

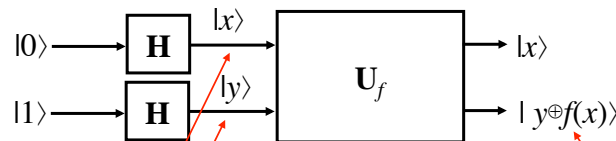
- Initialize Qubits to known state
- To exploit parallelism, place initialized qubits into a state of superposition
- Apply a series of evolutions of the quantum state of the system. This is accomplished by applying a series of quantum unitary operations to the quantum state
- Measure the quantum state – forcing it to collapse into an eigenket
- For deterministic output, the observable must be SHARP

## Deutsch's Problem

- Initially Place the Input Qubits into the Following States of Superposition:

$$|x\rangle = (|0\rangle + |1\rangle) / \sqrt{2} \quad |y\rangle = (|0\rangle - |1\rangle) / \sqrt{2}$$

- This is Accomplished via a Hadamard Transform (or the use of 2 Hadamard Gates):



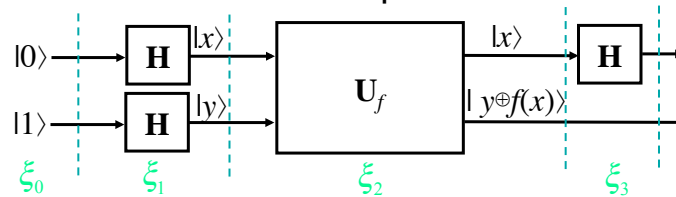
$$\mathbf{H} | 0 \rangle = (1 / \sqrt{2})(| 0 \rangle + | 1 \rangle)$$

$$\mathbf{H} | 1 \rangle = (1 / \sqrt{2})(| 0 \rangle - | 1 \rangle)$$

*As in Previous Example,  
Outputs are in Superposition  
State. Measurement here Yields  
Differing Results Probabilistically*

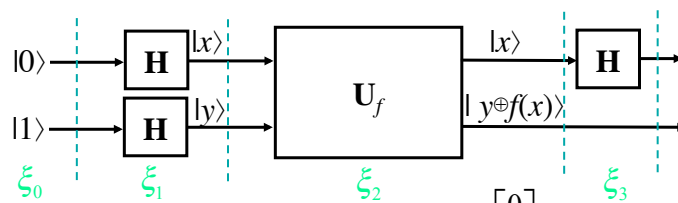
## Deutsch's Problem

- Must “Force” Output to Desired Basis State for a Deterministic Circuit/Algorithm to Result
- Accomplished by Placing an Additional Hadamard Gate at Output



- We Analyze this Quantum System (Circuit/ Algorithm) Stage-by-Stage

## Deutsch's Problem



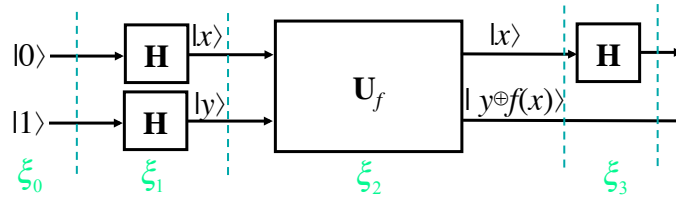
*XI*  
*KS-EYE*

$$|\xi_0\rangle = |01\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \otimes \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

- Transfer Matrix of First Stage:

$$\mathbf{G}_1 = \mathbf{H} \otimes \mathbf{H} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \otimes \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix}$$

## Deutsch's Problem



$$|\xi_1\rangle = |xy\rangle = \mathbf{G}_1 |01\rangle = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$$

$$|\xi_1\rangle = \frac{1}{2} (|00\rangle - |01\rangle + |10\rangle - |11\rangle) = [(|0\rangle + |1\rangle) / \sqrt{2}] [(|0\rangle - |1\rangle) / \sqrt{2}]$$

## Deutsch's Problem

- Note that:

$$|y \oplus f(x)\rangle$$

- and,

$$|y\rangle = (|0\rangle - |1\rangle) / \sqrt{2}$$

- thus,

$$\begin{aligned} |y \oplus f(x)\rangle &= (|0\rangle - |1\rangle) / \sqrt{2} \oplus f(x) \\ &= (|0\rangle \oplus f(x) - |1\rangle \oplus f(x)) / \sqrt{2} \end{aligned}$$

- using the fact:

$$|0 \oplus f(x)\rangle = |f(x)\rangle$$

$$|y \oplus f(x)\rangle = (|f(x)\rangle - |1 \oplus f(x)\rangle) / \sqrt{2}$$

## Deutsch's Problem

- In Problem Statement we know that:

$$f(x) = 1 \quad \text{OR} \quad f(x) = 0$$

- thus:

$$|1 \oplus f(x)\rangle = \begin{cases} |0\rangle, & f(x) = 1 \\ |1\rangle, & f(x) = 0 \end{cases}$$

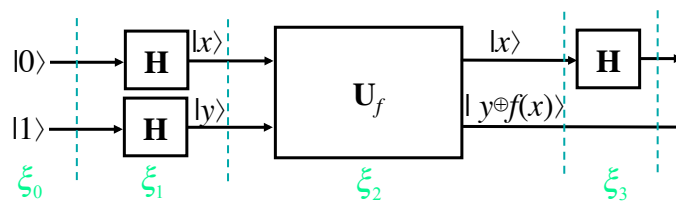
- yielding,

$$|y \oplus f(x)\rangle = (|f(x)\rangle - |1 \oplus f(x)\rangle) / \sqrt{2}$$

$$|y \oplus f(x)\rangle = \begin{cases} (|0\rangle - |1\rangle) / \sqrt{2}, & f(x) = 0 \\ -(|0\rangle - |1\rangle) / \sqrt{2}, & f(x) = 1 \end{cases}$$

$$|y \oplus f(x)\rangle = (-1)^{f(x)} (|0\rangle - |1\rangle) / \sqrt{2}$$

## Deutsch's Problem



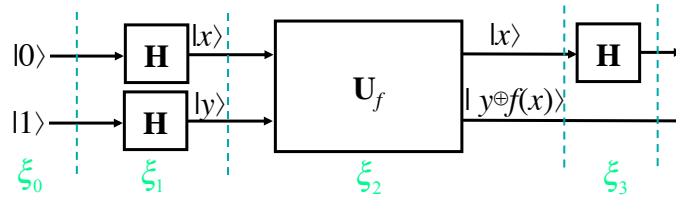
- When  $f(0)=f(1)=0$ :

$$|\xi_2\rangle = |x, y \oplus f(x)\rangle = |x\rangle \otimes |y \oplus f(x)\rangle$$

$$|x\rangle = \mathbf{H}|0\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$$

$$|y \oplus f(x)\rangle = \frac{|f(x)\rangle - |1 \oplus f(x)\rangle}{\sqrt{2}}$$

## Deutsch's Problem



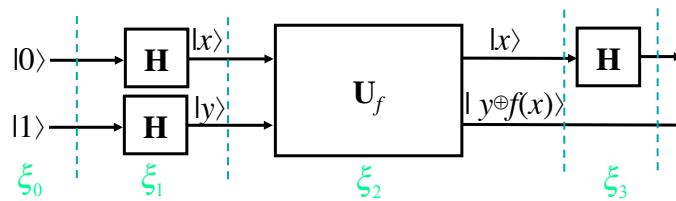
- Since  $f(x)=0$ :

$$|y \oplus f(x)\rangle = \frac{|f(x)\rangle - |1 \oplus f(x)\rangle}{\sqrt{2}} = \frac{|0\rangle - |1\rangle}{\sqrt{2}}$$

$$|\xi_2\rangle = |x\rangle \otimes |y \oplus f(x)\rangle = \left( \frac{|0\rangle + |1\rangle}{\sqrt{2}} \right) \otimes \left( \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right)$$

$$|\xi_2\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \otimes \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$$

## Deutsch's Problem

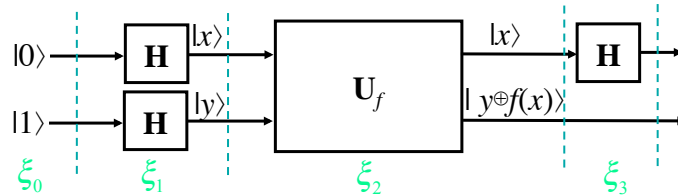


- Since  $f(x)=0$ :

$$|\xi_2\rangle = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \frac{1}{2} (|00\rangle - |01\rangle + |10\rangle - |11\rangle)$$

$$|\xi_2\rangle = \frac{1}{2} (|00\rangle - |11\rangle) = \left( \frac{|0\rangle + |1\rangle}{\sqrt{2}} \right) \left( \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right)$$

## Deutsch's Problem

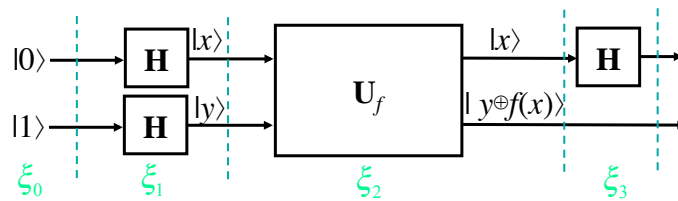


- When  $f(0)=f(1)$ :

$$|\xi_2\rangle = \begin{cases} \left[ \frac{|0\rangle + |1\rangle}{\sqrt{2}} \right] \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right], & f(0) = f(1) = 0 \\ - \left[ \frac{|0\rangle + |1\rangle}{\sqrt{2}} \right] \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right], & f(0) = f(1) = 1 \end{cases}$$

Obtained using similar derivation as that for  $f(x)=0$

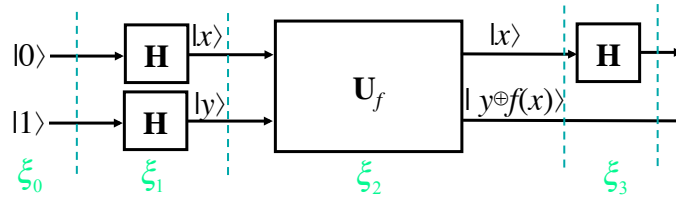
## Deutsch's Problem



- When  $f(0)=f(1)$ :

$$|\xi_2\rangle = \begin{cases} \frac{1}{2} [1 \ -1 \ 1 \ -1]^T, & f(0) = f(1) = 0 \\ -\frac{1}{2} [1 \ -1 \ 1 \ -1]^T, & f(0) = f(1) = 1 \end{cases}$$

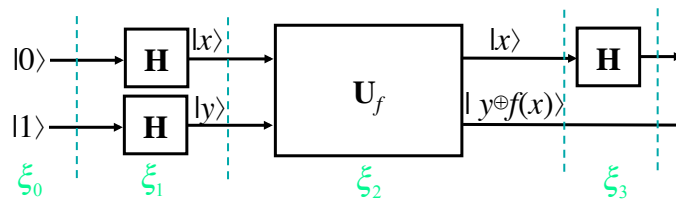
## Deutsch's Problem



- When  $f(0) \neq f(1)$ :

$$|\xi_2\rangle = \begin{cases} \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right] \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right], & f(0) = 0 \text{ and } f(1) = 1 \\ - \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right] \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right], & f(0) = 1 \text{ and } f(1) = 0 \end{cases}$$

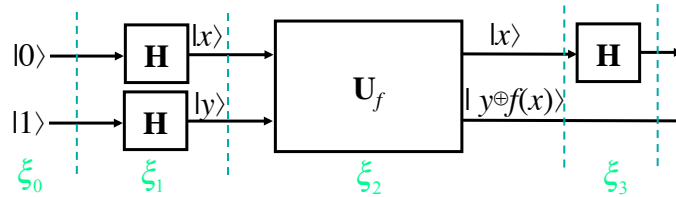
## Deutsch's Problem



- When  $f(0) \neq f(1)$ :

$$|\xi_2\rangle = \begin{cases} \frac{1}{2} [1 \ -1 \ -1 \ 1]^T, & f(0) = 0 \text{ and } f(1) = 1 \\ -\frac{1}{2} [1 \ -1 \ -1 \ 1]^T, & f(0) = 1 \text{ and } f(1) = 0 \end{cases}$$

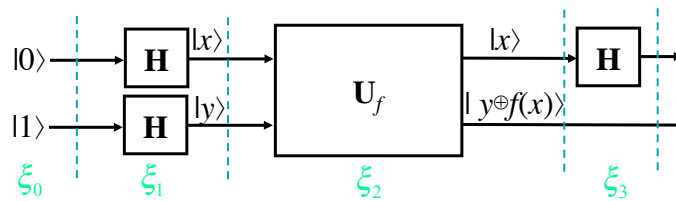
## Deutsch's Problem



- Combining the case where  $f(0)=f(1)$  and  $f(0)\neq f(1)$ :

$$|\xi_2\rangle = \begin{cases} \pm \left[ \frac{|0\rangle + |1\rangle}{\sqrt{2}} \right] \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right], & f(0) = f(1) \\ \pm \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right] \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right], & f(0) \neq f(1) \end{cases}$$

## Deutsch's Problem

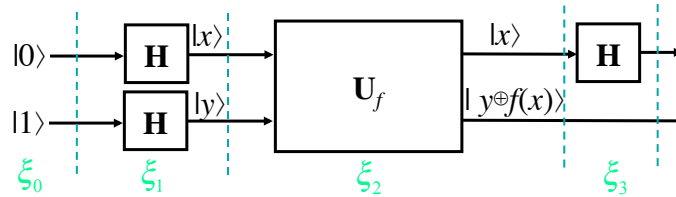


- Combining the case where  $f(0)=f(1)$  and  $f(0)\neq f(1)$ :

$$|\xi_2\rangle = \begin{cases} \pm \frac{1}{2} [1 \ -1 \ 1 \ -1]^T, & f(0) = f(1) \\ \pm \frac{1}{2} [1 \ -1 \ -1 \ 1]^T, & f(0) \neq f(1) \end{cases}$$



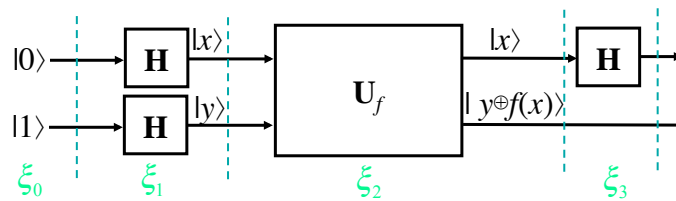
## Deutsch's Problem



- Transfer Matrix for the Final Stage:

$$\mathbf{H} \otimes \mathbf{I} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix}$$

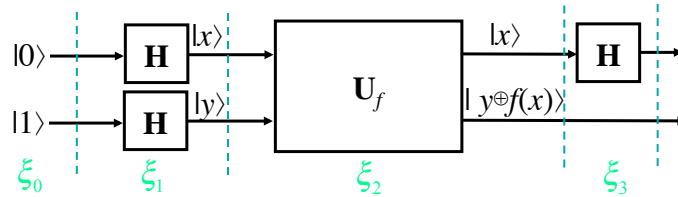
## Deutsch's Problem



- When  $f(0)=f(1)$ :

$$|\xi_3\rangle = \pm \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \pm \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} = \pm |0\rangle \frac{|0\rangle - |1\rangle}{\sqrt{2}}$$

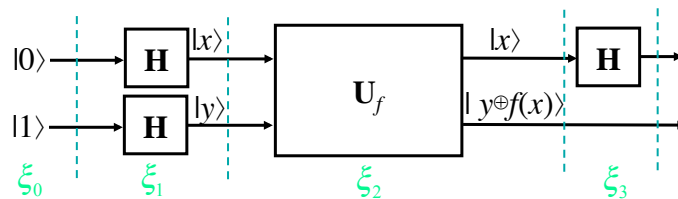
## Deutsch's Problem



- When  $f(0) \neq f(1)$ :

$$|\xi_3\rangle = \pm \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = \pm \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix} = \pm |1\rangle \frac{|0\rangle - |1\rangle}{\sqrt{2}}$$

## Deutsch's Problem

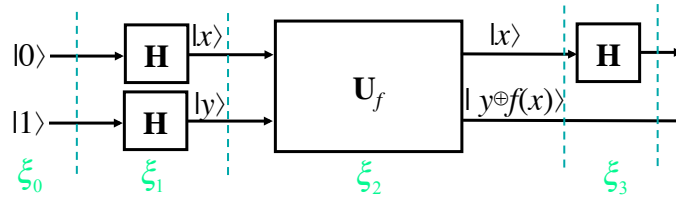


- Measuring First Output Qubit of Circuit Yields Answer to Problem

- For  $f(0) = f(1)$ :  $|\xi_3\rangle = \pm |0\rangle \frac{|0\rangle - |1\rangle}{\sqrt{2}} = \pm \frac{|00\rangle - |01\rangle}{\sqrt{2}}$

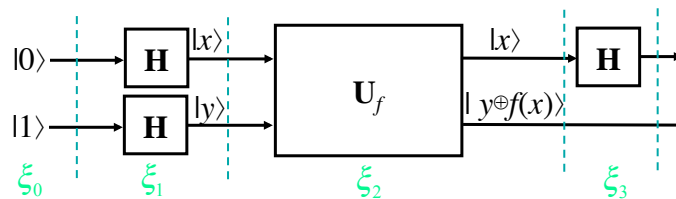
- For  $f(0) \neq f(1)$ :  $|\xi_3\rangle = \pm |1\rangle \frac{|0\rangle - |1\rangle}{\sqrt{2}} = \pm \frac{|10\rangle - |11\rangle}{\sqrt{2}}$

## Deutsch's Problem



- For  $f(0)=f(1)$ , Measuring First Output Qubit is Equally likely to give one of the two basis vectors  $|00\rangle$  or  $|01\rangle$  :
- For  $f(0)\neq f(1)$ , Measuring First Output Qubit is Equally likely to give one of the two basis vectors  $|10\rangle$  or  $|11\rangle$  :

## Deutsch's Problem



- Measuring First Output Qubit Yields the Answer
- First Output =  $|0\rangle$  means  $f(0)=f(1)$
- First Output =  $|1\rangle$  means  $f(0)\neq f(1)$
- Can Rewrite as:

$$|\xi_3\rangle = \pm |f(0) \oplus f(1)\rangle \left[ \frac{|0\rangle - |1\rangle}{\sqrt{2}} \right]$$

## Generalized Deutsch's Problem

- Original Deutsch Problem dealt with identification of one of four possible single bit functions:

$$\{0,1\} \rightarrow \{0,1\}$$

- This Problem is Generalized for Functions of the Form:

$$\{0,1\}^n \rightarrow \{0,1\}$$

- The Quantum Solution of this Generalized Problem is Called the Deutsch-Jozsa Algorithm

## Deutsch-Jozsa Algorithm

- Functions of this form can be classified as balanced or unbalanced

$$\{0,1\}^n \rightarrow \{0,1\}$$

- Balanced functions are those that Output a “1” for half the input terms and a “0” for the other half
- Unbalanced Functions Output a Constant “1” or “0” Regardless of the input terms
- For a Function whose domain consists of  $n$  bitstrings, there are 2 Unbalanced Functions
- For a Function whose domain consists of  $N$  bitstrings, there are  $N$  Unbalanced Functions

## Number of Balanced Functions

- For a Function whose domain consists of  $n$  bitstrings, there are  $N$  Unbalanced Functions
- $N$  can be Computed using the binomial coefficient:

$$N = \binom{2^n}{2^{n-1}}$$

- This is a “special” coefficient known as the “central binomial coefficient”
- The central binomial coefficient is of the following form and obeys the identity:  $\binom{2x}{x} = \frac{(2x)!}{(x!)^2}$

## Number of Balanced Functions

- Using the property of the central binomial coefficient:

$$N = \binom{2^n}{2^{n-1}} = \frac{2^n!}{(n!)^2}$$

- The sequence of central binomial coefficients is:  
1, 2, 6, 20, 70, 252, 924, 3432, 12870, 48620, ...
- Some properties are the generating function:

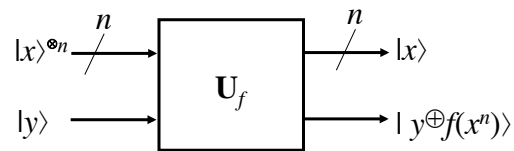
$$\frac{1}{\sqrt{1-4x}} = 1 + 2x + 6x^2 + 20x^3 + 70x^4 + 252x^5 + \dots$$

- Behavior in the limit (using Stirling's formula):

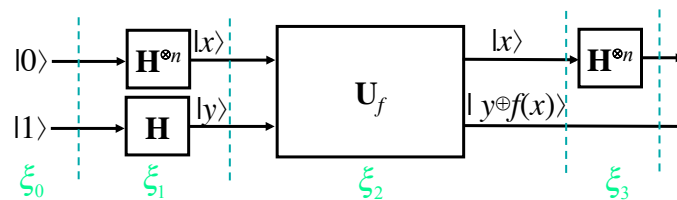
$$\lim_{n \rightarrow \infty} \binom{2^n}{2^{n-1}} = \frac{2^{n+1}}{\sqrt{\pi 2^{n-1}}}$$

## Deutsch-Jozsa Algorithm

- $U_f$  is Sometimes Called the “Oracle”
- The Oracle has a function embedded in it that is either balanced or unbalanced (constant)
- Note this does not include all possible functions!



## Deutsch-Jozsa Algorithm



- This is NOT a particularly useful algorithm
- It is a good example to show how an exponential problem (in terms of Turing computation) can be accomplished in constant time with a quantum computer